

Study of Real Time Gait Analysis using Support Vector Regression with ACO

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Abstract- Gait analysis entails the quantitative evaluation of a person's locomotion patterns. It is a powerful tool for therapists treating patients with impairments associated with neurological disorders or individuals who have undergone a surgical procedure in their lower extremities. In sports medicine and sport biomechanics, gait assessments are used to mitigate the risk of injuries, improve athletes' running technique, and design orthotic devices and footwear. Mean Absolute Error and Standard Deviation are become high in 10-fold cross-validation and Leave-one-out cross-validation. Traditionally, gait analysis is performed using expensive laboratory equipment such as optical motion-capture systems, force plates, or electronic walk a ways that provide accurate estimates but are restricted to controlled indoor environments. Footwear-based motion tracking systems, a type of wearable sensor networks (WSN), allow for measurements of kinematic and kinetic gait data over any distance or path, in a multiplicity of maneuvers, and over extended time periods. The validity of the computational models was assessed through repeated-measures, using MAE of SL, SV, and FC as dependent variables. MAE was selected as the error metric because it is extensively used in the validation of wearable sensors. The proposed method SVR-ACO (Support Vector Regression with Ant Colony Optimization) effectively works on subject specific and generic condition. Reduce Mean Absolute Error (MAE) in (10-fold cross-validation) generic situation up to 31.2% and 36.42% respectively and reduce Standard Deviation (SD) in (10-fold cross-validation) subject specific and (Leave-one-out cross-validation) subject specific and (Leave-on

Key Terms— MAE (Mean Absolute Error), SD (Standard Deviation), Subject Specific, Generic, SVR (Support Vector Regression), ACO (Ant Colony Optimization).

I. INTRODUCTION

Gait analysis entails the quantitative evaluation of a person's locomotion patterns. It is a powerful tool for therapists treating patients with impairments associated with neurological disorders or individuals who have undergone a surgical procedure in their lower extremities. In sports medicine and sport biomechanics, gait assessments are used to mitigate the risk of injuries, improve athletes' running technique, and design orthotic devices and footwear. Traditionally, gait analysis is performed using expensive laboratory equipment such as optical motion-capture systems, force plates, or electronic walk a ways that provide accurate estimates but are restricted to controlled indoor environments. Footwear-based motion tracking systems, a type of wearable sensor networks (WSN), allow for measurements of kinematic and kinetic gait data over

any distance or path, in a multiplicity of maneuvers, and over extended time periods. Because they fit in the wearer's shoes, these devices are portable, unobtrusive to the user, and enable gait assessments as well as activity monitoring in unconstrained, dailylife environments. For this reason, footwear-based systems represent a promising alternative to laboratory equipment, which is better suited for capturing gait in uncontrolled, real life scenarios. Applications of footwear-based systems include gait characterization in the elderly and in patients with movement disorders, fall risk assessments and detection and activity classification in older adults, as well as gait rehabilitation. In sports medicine, footwear based systems can provide relevant information about weight bearing and weight shifting patterns that are precursors of injuries.



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II. PREVIOUS WORK

Customarily, inertial estimation units-(IMU) based human joint point assessment requires deduced information about sensor arrangement or explicit alignment movements. Moreover, magnetometer estimations can become temperamental inside. Without magnetometers, notwithstanding, IMUs do not have a heading reference, which prompts surreptitiously capacity issues. This paper proposes a without magnetometer assessment technique, which gives alluring notice capacity characteristics under joint kinematics that adequately energize the lower body levels of opportunity. (Timothy McGrath and Leia Stirling; 2020)

Wearable sensors have been proposed as options in contrast to customary research facility hardware for minimal effort and convenient constant stride examination in unconstrained conditions. In any case, the moderate exactness of these frameworks as of now restricts their boundless use. In this paper, we show that help vector relapse (SVR) models can be utilized to separate precise evaluations of principal step boundaries (i.e., step length, speed and foot freedom), from exceptionally designed instrumented insoles (SportSole) during strolling and running assignments. Also, these learning-based models are strong to between subject changeability, in this way making it superfluous to gather subject-explicit preparing information. (Huanghe Zhangy, Yi Guoz, Damiano Zanottoy; 2019)

Quantitative stride appraisal regularly includes optical movement catch frameworks and power plates, which bring about high working expenses. Footwear-based movement global positioning frameworks can give a versatile and moderate answer for constant walk examination in unconstrained conditions. In any case, the generally low precision of these frameworks actually addresses a boundary to their far reaching use. (Huanghe Zhang, Mey Olivares Tay; 2018)

Inertial sensor float is generally amended on a single sensor unit level. At the point when various sensor units are utilized, common data from various units can be misused for float amendment. This investigation presents a technique for a float decreased assessment of three dimensional (3D) portion directions and joint plots for movement catch of profoundly powerful developments as present in numerous games. (Benedikt Fasel, Jorg Sporri, Julien Chardonnens, Josef Kroll, Erich Muller and Kamiar Aminian; 2017)

III. PROBLEM IDENTIFICATION

The recognized issue in existing work is according to the accompanying:

1. Mean Absolute Error become high in (10-overlay cross-approval) subject explicit and (Leave-one-out cross-approval) nonexclusive circumstance.

2. Standard Deviation is high in (10-overlay crossapproval) subject explicit and (Leave-one-out crossapproval) nonexclusive circumstance.

IV. RESEARCH OBJECTIVES

The goals of this proposal work are as per the following:

1. To decrease Mean Absolute Error (MAE) in (10overlay cross-approval) subject explicit and (Leaveone-out cross-approval) nonexclusive circumstance.

2. To lessen Standard Deviation (SD) in (10-overlay cross-approval) subject explicit and (Leave-one-out cross-approval) nonexclusive circumstance.

V. METHODOLOGY

The algorithm of proposed methodology (SVR-ACO) is as follows:

Stage 1: Importing the libraries

We'll import the libraries we'll have to build the ML model in this first stage. The matplotlib library and the NumPy library are likewise imported. We've likewise added the Pandas library to assist with information examination.

Stage 2: Importing the dataset.



We'll utilize pandas to store the information from my github storehouse as a Pandas DataFrame utilizing the capacity "pd.read csv" in this stage. We go through our information and put the autonomous variable (x) in the section "Long stretches of Study" and the reliant variable (y) in the last segment, "Imprints" not out of the ordinary.

To designate these lists to X and Y, we cut the DataFrame with the corresponding.iloc work. The autonomous variable for this situation is Hours of Study, which is designated to X. The last section, Marks, is the needy variable not out of the ordinary, and it is relegated to y. We'll utilize reshape to reshape the variable y into a section vector (-1,1).

Stage 3: Feature Scaling

Most of the information accessible is regularly of various reaches and extents, making it hard to develop a model. Therefore, the informational index should be standardized to a greater region all together for the model to be more dependable during preparing. The information in this dataset has been normalized to little qualities close to nothing. For instance, the score of 87.23092513 is standardized to 1.00475931 and score of 53.45439421 is standardized to - 1.22856288.

In most customary Regression and Classification models, Feature Scaling is regularly done inside. Since Support Vector Machine is an only sometimes utilized class, the information is standardized to a thin reach.

Stage 4: Use the Training set to prepare the Support Vector Regression model.

We should consistently partition the information into the preparation set and the test set while building a ML model. Out of 100 columns, 80 lines are utilized for preparing and the model is tried on the excess 20 lines as given by the condition, test_size=0.2

Stage 5: Use the Training set to prepare the Support Vector Regression model.

The SVM work is imported and allotted to the relapse variable. The rbf (Radial Basis Function) bit is utilized. The SVR model is given a non-linearity by utilizing the RBF part. This is fundamental because of the non-straight nature of our information. By reshaping the factors X train and y train, the regressor.fit is utilized to fit them.

Stage 6: Predicting the Test set Results

We'll utilize the SVR model we created to anticipate the test set's scores in this stage. The X test esteems are anticipated utilizing the regressor.predict calculation. The projected qualities are alloted to y_pred. We presently have two arrangements of information: y_test (genuine qualities) and y_pred (anticipated qualities) (anticipated qualities).

Stage 7: Comparing the Test Set with Predicted Values

In this stage, we'll utilize a Pandas Data Frame to analyze the y_test values as Real Values and the y_pred values as Predicted Values for every X test. We can see that the normal qualities are essentially not the same as the test set's genuine qualities, so we can gather that this model is definitely not an ideal fit for the outcomes.

Stage 8: Optimize the get information from SVR model

Set Parameters, Initialize pheromone trails

8.1 Construct Ant Solutions

An insect will move from hub I to hub j with likelihood

A bug will move from center point I to center point j with probability

$$p_{i,j} = \frac{(\tau_{i,j}^{\alpha})(\eta_{i,j}^{\beta})}{\sum (\tau_{i,j}^{\alpha})(\eta_{i,j}^{\beta})}$$

Where $\tau i, j$ is the measure of pheromone nervous I, j



 α is a boundary to control the impact of $\tau i,j$

- $\eta i,j$ is the allure of edge I, j (normally 1/di,j)
- β is a boundary to control the impact of $\eta i, j$
- 8.2 Daemon Actions (discretionary)
- 8.3 Update Pheromones

Measure of pheromone is refreshed by the condition

$$\tau i, j = (1 - \rho)\tau i, j + \Delta \tau i, j$$

Where $\tau i, j$ is the measure of pheromone on a given edge I, j

 ρ is the pace of pheromone dissipation

 $\Delta \tau i, j$ is the measure of pheromone stored, normally given by

$$\Delta \tau_{i,j}^{k} = \begin{cases} 1/L_{k} & \text{if ant } k \text{ travels on edge } i, j \\ 0 & \text{otherwise} \end{cases}$$

Where Lk is the expense of the kth insect's visit (normally length).

Stage 9: Visualizing the SVR results

In this last advance, we will imagine the SVR model that was assembled utilizing the given information and plot the estimations of "y" and "y_pred" on the diagram to picture the outcomes.

VI. RESULTS AND ANALYSIS

To start with, the examination was directed on models prepared and tried on information gathered during Session 1. Thusly, similar step boundaries were registered once more, this time by applying models prepared utilizing Session 1 information to crude information gathered in Session 2. At that point, the ANOVA models were run on the new gauges. This progression was important to decide if SS models would beat GN models during multimeeting tests.

Table 1: Estimation of MAE and SD in Session 1 (Walking) for Subject-Specific

S1:	SVR-GA		SVR-ACO (Proposed)	
Walking	MAE	SD	MAE	SD
SL	1.53	0.72	1.07	0.31
SV	1.4	0.41	0.9	0.12
FC	0.17	0.04	0.02	0.02

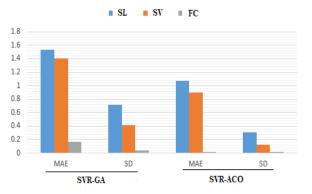


Figure 1: Graphical Analysis of MAE and SD in Session 1 (Walking) for Subject-Specific

In Subject Specific, The above assessment of MAE and SD of Session 1 (Walking) shows that proposed strategy (SVR-ACO) lessen estimation of MAE for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 30.06%, 35.7%, 88.3% separately. Likewise, proposed strategy (SVR-ACO) decrease estimation of SD for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 56.94%, 70.73%, half separately.

Table 2: Estimation of MAE and SD in Session 1 (Running) for Subject-Specific

S1:	SVR-GA		SVR-ACO (Proposed)	
Running	MAE	SD	MAE	SD



SL	2.37	0.65	1.98	0.41
SV	3.10	0.57	2.72	0.29
FC	0.58	0.28	0.35	0.11

In Subject Specific, The above assessment of MAE and SD of Session 1 (Running) shows that proposed strategy (SVR-ACO) decrease estimation of MAE for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 30.06%, 35.7%, 88.3% separately.

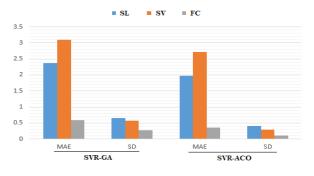


Figure 2: Graphical Analysis of MAE and SD in Session 1 (Running) for Subject-Specific

In Subject Specific, The above assessment of MAE and SD of Session 1 (Running) shows that proposed strategy (SVR-ACO) lessen estimation of MAE for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 16.45%, 12.25%, 39.65% separately. Likewise, proposed strategy (SVR-ACO) lessen estimation of SD for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 36.9%, 49.12%, 60.71% individually.

Table 3: Estimation of MAE and SD in Session 2 (Walking) for Subject-Specific

S2:	SVR-GA		SVR-ACO (Proposed)	
Walking	MAE	SD	MAE	SD
	2.14	0.87	1.87	0.67
SV	1.7	0.31	0.62	0.13
FC	0.32	0.13	0.15	0.02

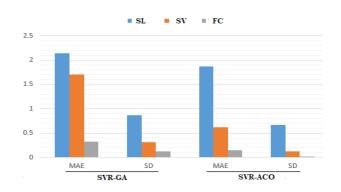


Figure 3: Graphical Analysis of MAE and SD in Session 2 (Walking) for Subject-Specific

In Subject Specific, The above assessment of MAE and SD of Session 2 (Walking) shows that proposed strategy (SVR-ACO) decrease estimation of MAE for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 12.61%, 63.52%, 53.12% individually. Along these lines, proposed strategy (SVR-ACO) lessen estimation of SD for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 22.98%, 58.06%, 84.61% individually.

Table 4: Estimation of MAE and SD in Session 2 (Running) for Subject-Specific

S2:	SVR-GA		SVR-ACO (Proposed)	
Running	MAE	SD	MAE	SD
SL	4.39	1.60	3.95	0.92
SV	6.26	3.07	5.73	2.63
FC	1.37	0.94	1.13	0.78

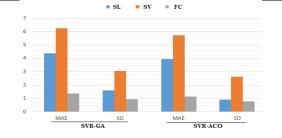


Figure 4: Graphical Analysis of MAE and SD in Session 2 (Running) for Subject-Specific



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In Subject Specific, The above assessment of MAE and SD of Session 2 (Running) shows that proposed technique (SVR-ACO) decrease estimation of MAE for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 10.02%, 8.46%, 17.5% separately. Along these lines, proposed technique (SVR-ACO) decrease estimation of SD for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 42.5%, 14.33%, 17.02% individually.

Table 5: Estimation of MAE and SD in Session 1 (Walking) for Generic

	SVR-GA		SVR-ACO	
S1:			(Proposed)	
Walking	MAE	SD	MAE	SD
SL	2.1	0.85	1.66	0.44
SV	1.88	0.56	1.23	0.21
FC	0.3	0.17	0.05	0.03

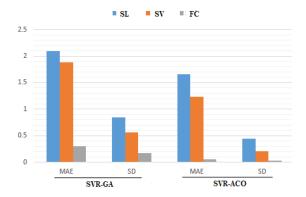


Figure 5: Graphical Analysis of MAE and SD in Session 1 (Walking) for Generic

In Generic, The above assessment of MAE and SD of Session 1 (Walking) shows that proposed strategy (SVR-ACO) decrease estimation of MAE for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 20.95%, 34.57%, 83.3% individually. Along these lines, proposed technique (SVR-ACO) diminish estimation of SD for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 48.23%, 62.5%, 82.35% individually.

Table 6: Estimation of MAE and SD in Session 1 (Running) for Generic

S1:	SVR-GA		SVR-ACO (Proposed)	
Walking	MAE	SD	MAE	SD
SL	5.16	1.2	4.96	0.61
SV	7.56	2.01	6.6	1.74
FC	1.38	0.63	1.08	0.49

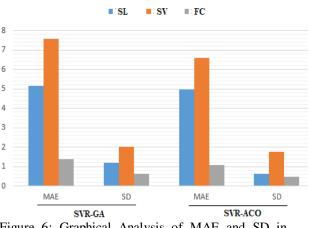


Figure 6: Graphical Analysis of MAE and SD in Session 1 (Running) for Generic

In Generic, The above assessment of MAE and SD of Session 1 (Running) shows that proposed strategy (SVR-ACO) decrease estimation of MAE for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 3.87%, 12.69%, 21.7% separately. Along these lines, proposed technique (SVR-ACO) diminish estimation of SD for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 49.16%, 13.43%, 22.2% separately.

Table 7: Estimation of MAE and SD in Session 2 (Walking) for Generic

S1:	SVR-GA		SVR-ACO (Proposed)	
Walking	MAE	SD	MAE	SD



SL	2.25	0.59	1.92	0.41
SV	2.18	0.57	1.86	0.38
FC	0.44	0.21	0.32	0.11

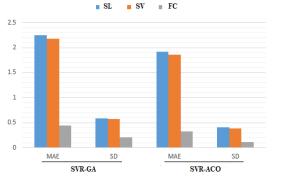


Figure 7: Graphical Analysis of MAE and SD in Session 2 (Walking) for Generic

In Generic, The above assessment of MAE and SD of Session 2 (Walking) shows that proposed strategy (SVR-ACO) decrease estimation of MAE for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 14.67%, 14.4%, 27.27% separately. Likewise, proposed strategy (SVR-ACO) lessen estimation of SD for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 10.5%, 33.3%, 47.6% individually.

Table 8: Estimation of MAE and SD in Session 2(Running) for Generic

S1:	SVR-GA		SVR-ACO (Proposed)	
Walking	MAE	SD	MAE	SD
SL	6.87	2.41	5.91	1.88
SV	10.46	3.76	8.77	2.81
FC	1.76	0.74	1.11	0.33

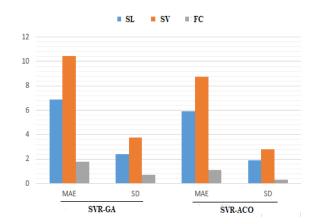


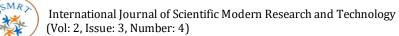
Figure 8: Graphical Analysis of MAE and SD in Session 2 (Running) for Generic

In Generic, The above assessment of MAE and SD of Session 2 (Running) shows that proposed strategy (SVR-ACO) lessen estimation of MAE for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 13.97%, 16.15%, 36.93% individually. Along these lines, proposed strategy (SVR-ACO) diminish estimation of SD for Stride Length (SL), Stride Velocity (SV), Foot Clearance (FC) for example 22%, 25.26%, 55.4% individually.

VII. CONCLUSION

This technique to remove precise appraisals of central step to-walk stride boundaries from specially designed instrumented insoles through relapse models during strolling and running assignments. The outcomes demonstrated that both SS and GN AI relapse models (SVR-ACO) could improve exactness while likewise showing better mediator and testretest unwavering quality than direct models. Since applying GN relapse models doesn't need subjectspecific preparing information, these findings have significant ramifications for existing wearable gadgets, other than giving additional proof that wearable frameworks might be a substantial option in contrast to lab hardware for surveying an essential arrangement of walk boundaries in unconstrained conditions. The finishes of this postulation work are as per the following:

1. Diminish Mean Absolute Error (MAE) in (10overlap cross-approval) subject explicit and (Leave-



one-out cross-approval) nonexclusive circumstance up to 31.2% and 36.42% individually.

2. To decrease Standard Deviation (SD) in (10overlap cross-approval) subject explicit and (Leaveone-out cross-approval) nonexclusive circumstance up to 41.82% and 21.3% separately.

VIII. FUTURE SCOPES

This work was formed as a consider chart and actualized a structure which utilized best in class IMU assessment procedures. The created structure considers expressive consideration of new kinematics models, planned to give an establishment to future work to expand upon. Future work will incorporate approving exactness, accuracy, and test-retest dependability of the SVR-ACO models in strolling and running undertakings, when a subject's own reference step information are not accessible to adjustment models. prepare these Future examinations will likewise be led to approve these models with neurotic step.

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